

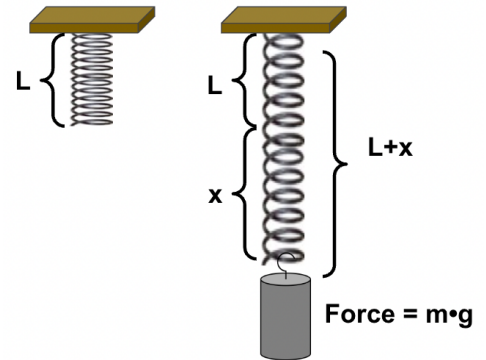
## Vibrating Mass on a Spring Lesson Notes

### Learning Outcomes

- How does the force, acceleration, speed, position, and kinetic and potential energy of a vibrating mass on a spring change over the course of a cycle?

### Hooke's Law

- In the absence of a force, a spring assumes a natural length.
- When a force is applied (e.g., by adding a mass), the spring stretches (or compresses) by a distance of  $x$ .
- The spring exerts a force in the opposite direction as the direction of its stretch (or compression).
- Hooke's Law states the relationship between the amount of stretch and the amount of force applied by the spring.

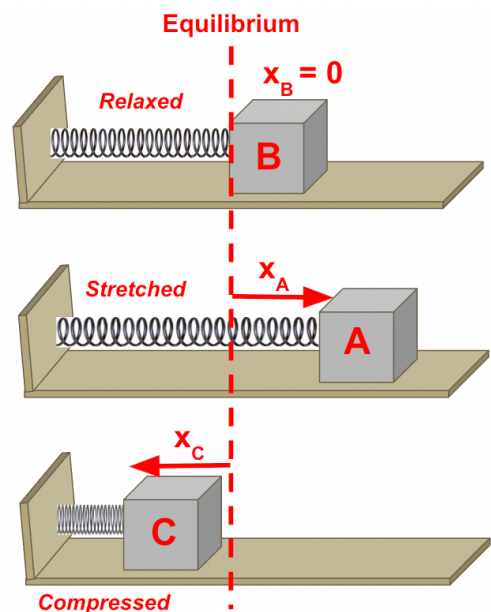
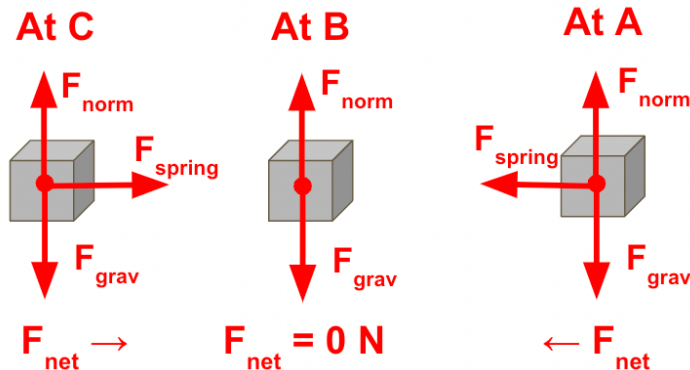


$$F_{\text{spring}} = -k \cdot x$$

$k$  = spring constant (N/m)  
 $x$  = displacement

### Force Analysis – Horizontal Springs

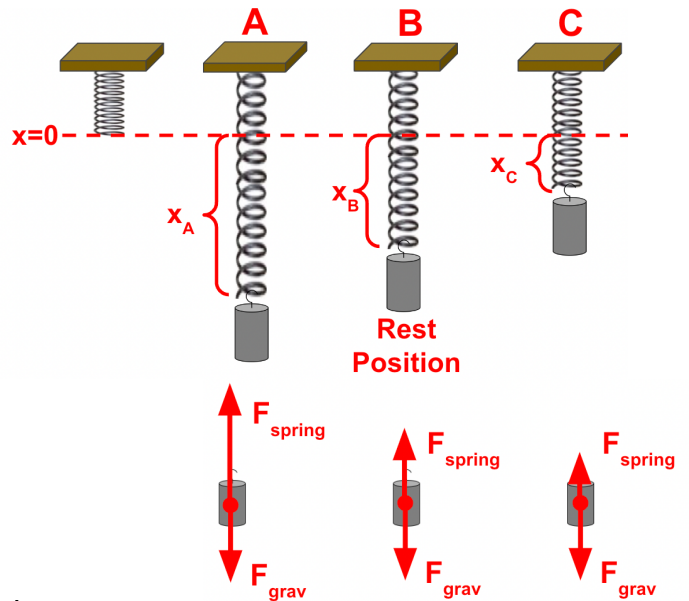
- Consider a mass attached to a **relaxed** spring on a friction-free air table.
- If the spring is stretched and then released, it will begin vibrating back and forth between its two extremes.



## Force Analysis – Vertical Springs

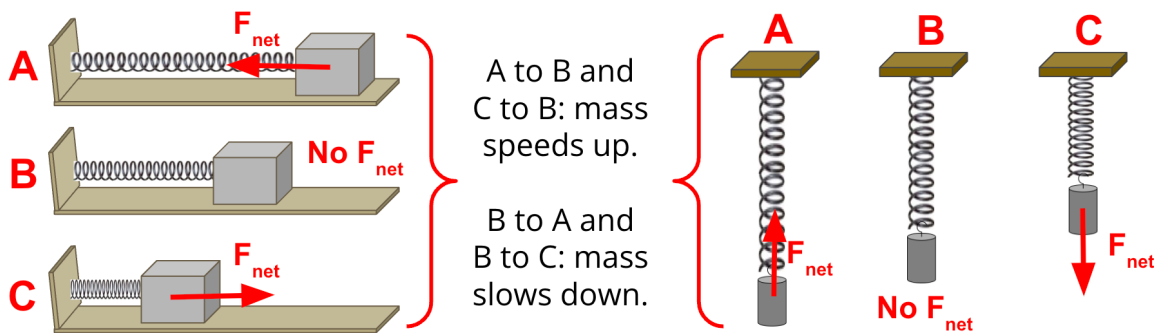
- A spring is suspended vertically and assumes its unstretched length.
- A mass is hung on the spring and lowered to a **rest position**. The spring is stretched to position B.
- The mass is pulled to A and released from rest. It oscillates back and forth between positions A and C.

$F_{\text{grav}}$ : always down       $F_{\text{spring}}$ : always up  
 $F_{\text{net}}$ : always towards B (restoring force)



## Speed and Acceleration

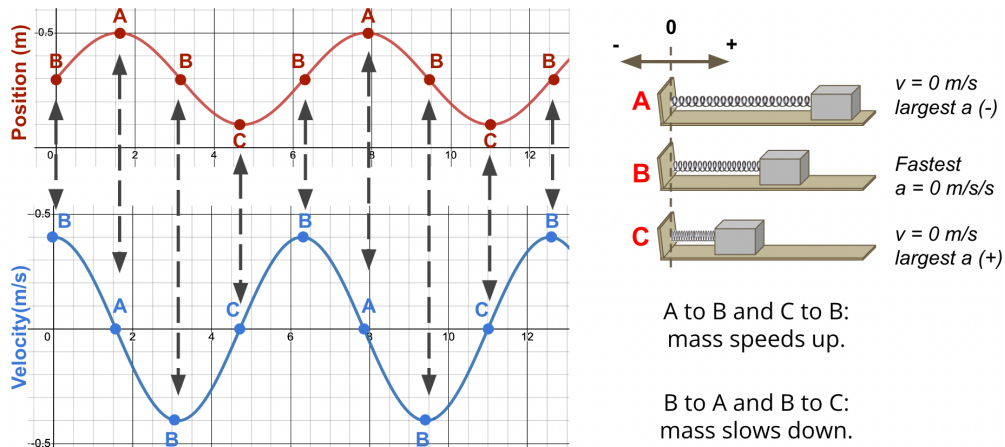
As the mass vibrates back and forth, its speed changes. The speed is 0 m/s at the extreme positions and a maximum value at the equilibrium position.



The acceleration is in the direction of and proportional to the net force (restoring force). Like  $F_{\text{net}}$ , acceleration is always directed towards the equilibrium position. And like  $F_{\text{net}}$ , acceleration is largest at the extremes and 0 m/s/s at the equilibrium position.

## Sinusoidal Nature of a Mass on a Spring

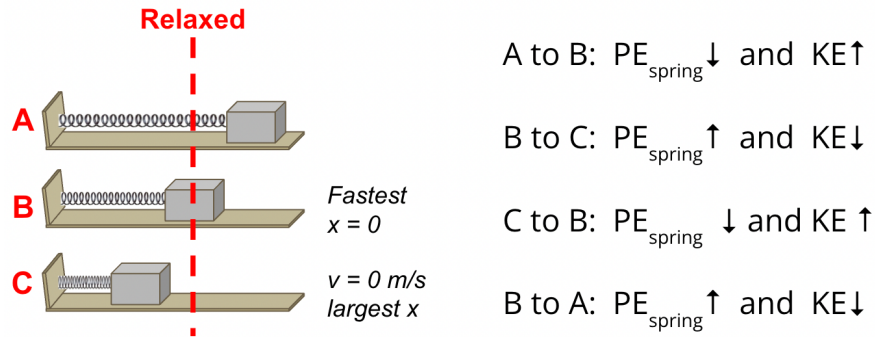
Position and velocity (and more) change periodically as a function of the sine of time.



## Energy Analysis (Horizontal Springs)

As the mass vibrates back and forth between extremes, energy is changing from **elastic potential energy** ( $PE_{\text{spring}}$ ) and **kinetic energy** ( $KE$ ).

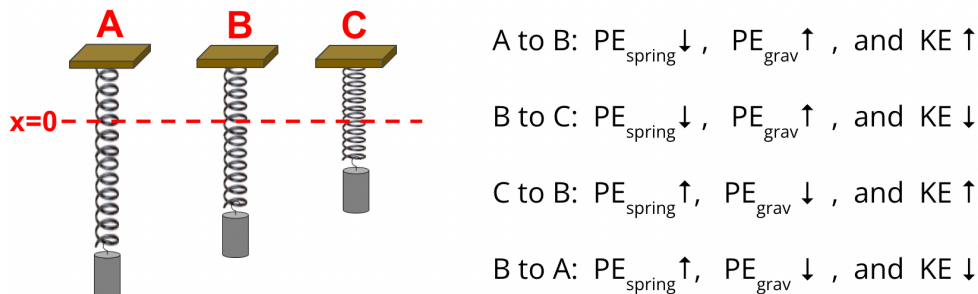
- **Kinetic energy** (speed dependent) is greatest at position B.
- **Elastic potential energy** (stretch/compression dependent) is greatest at positions A and C.



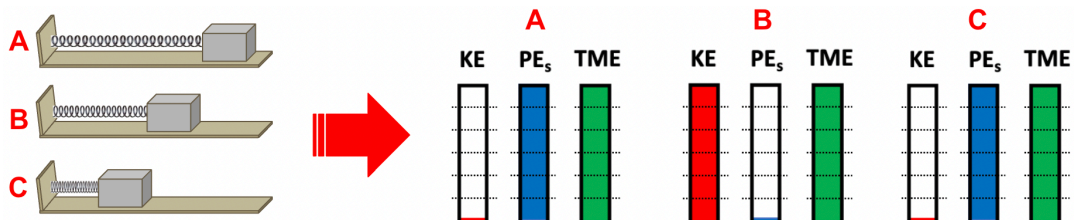
## Energy Analysis (Vertical Springs)

As a mass on a vertical spring vibrates between extremes, energy is changing between **gravitational potential energy** ( $PE_{\text{grav}}$ ), **elastic potential energy** ( $PE_{\text{spring}}$ ) and **kinetic energy** ( $KE$ ).

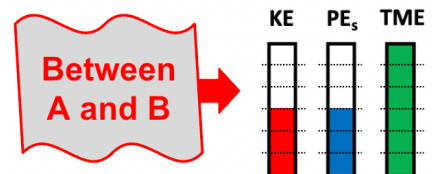
- **Kinetic energy** (speed dependent) is greatest at position B.
- **Gravitational potential energy** (height dependent) is greatest at positions C.
- **Elastic potential energy** (stretch/compression dependent) is greatest at position A and least at position C.



## Energy Bar Charts



As the **kinetic energy** ( $KE$ ) increases, the **elastic potential energy** ( $PE_{\text{spring}}$ ) decreases, but the **total mechanical energy** ( $TME$ ) remains constant. And vice versa.



## Period and Frequency

The period (**T**) of vibration of a spring-mass system depends upon the spring constant (**k**) of the spring and the mass (**m**) of the vibrating object.

$$T = 2 \cdot \pi \cdot \sqrt{m/k}$$

More massive objects will have longer periods.

Stiffer springs (larger **k**) will have shorter periods.

The frequency (**f**) of vibration is the reciprocal of the period and calculated as ...

$$f = 1/T = \sqrt{k/m} / 2 \cdot \pi$$